**VF PACKAGE** 

(TOP VIEW)

GND

32 31 30 29 28 27 26 25

9 10 11 12 13 14 15 16

OVRCUR2 DM2 PWRON2

OVRCUR1 DM1

DP0 ∏

V<sub>C</sub>C

RESET

BUSPWR [

EEDATA/GANGED Π

EECLK [

GND [

2 рмо П

3

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24 **□** DP4

23 ∏ DM4

20 **∏** DP3

19 ∏ DM3

17

22 OVRCUR4

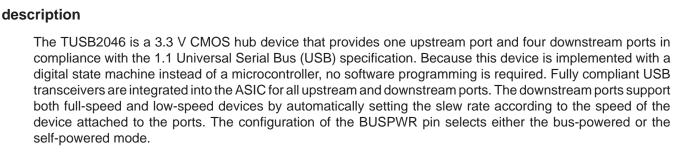
18 OVRCUR3

PWRON3

21 PWRON4



- 32-Pin TQFP Package With a 0.8 mm Pin Pitch
- 3.3-V Low Power ASIC Logic
- **Integrated USB Transceivers**
- **State Machine Implementation Requires No Software Programming**
- One Upstream Port and Four Downstream **Ports**
- All Downstream Ports Support Full-Speed and Low-Speed Operations
- **Two Power Source Modes** 
  - **Self-Powered Mode**
  - **Bus-Powered Mode**
- **Power Switching and Over-current** Reporting is Provided Ganged or Per Port
- **Supports Suspend and Resume Operations**
- Supports Programmable Vendor ID and Product ID With External Serial EEPROM
- 3-State EEPROM Interface Allows EEPROM **Sharing**
- Push-Pull Outputs for PWRON Eliminate the Need for External Pullup Resistors
- Noise Filtering on OVRCUR Provides Immunity to Voltage Spikes
- Package Pinout Allows 2-Layer PCB
- Low EMI Emission Achieved by a 6-MHz **Crystal Input**
- Migrated From Proven TUSB2040 Hub
- Lower Cost Than the TUSB2040 Hub





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# TUSB2046 4-PORT HUB FOR THE UNIVERSAL SERIAL BUS WITH OPTIONAL SERIAL FEPROM INTERFACE

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#### description (continued)

Configuring the GANGED input determines the power switching and over-current detection modes for the downstream ports. External power management devices such as the TPS2044 are required to control 5 V source to the downstream ports according to the corresponding values of the PWRON pin. Upon detecting any over-current conditions, the power management device sets the corresponding OVRCUR pin of the TUSB2046 to a logic low. If GANGED is high, all PWRON outputs switch together and if any OVRCUR is activated, all ports transition to power off state. If GANGED is low, the PWRON outputs and OVRCUR inputs operate on a per port basis.

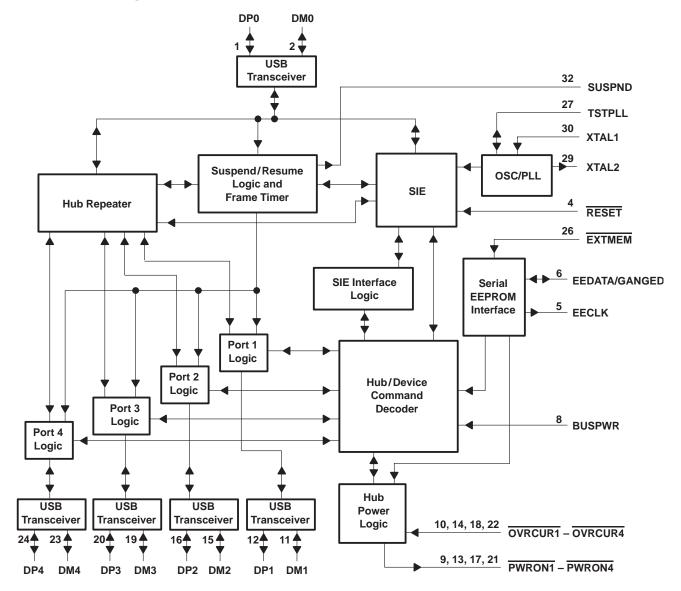
Low EMI emission is achieved because the TUSB2046 is able to utilize a 6 MHz crystal input. Connect the crystal as shown in Figure 7. An internal PLL then generates the 48 MHz clock used to sample data from the upstream port and to synchronize the 12 MHz used for the USB clock. If low power suspend and resume are desired, a passive crystal or resonator must be used. However, a 6-MHz oscillator may be used by connecting the output to the XTAL1 terminal and leaving the XTAL2 terminal open. The oscillator TTL output should not exceed 3.6-V.

The EXTMEM pin enables or disables the optional EEPROM interface. When the EXTMEM pin is high, the product ID (PID) displayed during enumeration is 'General-Purpose USB Hub'. For this default, pin 5 is disabled and pin 6 functions as the GANGED input pin. If custom PID and Vendor ID (VID) descriptors are desired, the EXTMEM pin must be low (EXTMEM = 0). For this configuration, pin 5 and pin 6 function as the EEPROM interface with pin 5 and pin 6 functioning as the EECLK and EEDATA, respectively. See Table 1 of this datasheet for a description of the EEPROM memory map.

Other useful features of the TUSB2046 include a package with a 0.8 mm pin pitch for easy PCB routing and assembly, push-pull outputs for the PWRON pins eliminate the need for pullup resistors required by traditional open collector I/Os, and OVRCUR pins have noise filtering for increased immunity to voltage spikes. For a concise list of features, please see the above bullet listing.



# functional block diagram



### **Terminal Functions**

TERMINAL		Ī			
NAME VF		1/0	DESCRIPTION		
BUSPWR	8	I	Power source indicator. BUSPWR is an active high input that indicates whether the downstream ports southeir power from the USB cable or a local power supply. For the bus-power mode, this pin should be put to 3.3 V, and for the self-powered mode, this pin should be pulled low. Input must not change dynamic during operation.		
DM0	2	I/O	Root port USB differential data minus. DM0 paired with DP0 constitutes the upstream USB port.		
DM1 – DM4	11, 15, 19, 23	I/O	USB differential data minus. DM1 – DM4 paired with DP1 – DP4 support up to four downstream USB ports.		
DP0	1	I/O	Root port USB differential data plus. DP0 paired with DM0 constitutes the upstream USB port.		
DP1 – DP4	12, 16, 20, 24	I/O	USB differential data plus. DP1 – DP4 paired with DM1 – DM4 support up to four downstream USB ports.		
EECLK	5	0	EEPROM serial clock. When EXTMEM is high, the EEPROM interace is disabled. The EECLK pin is disabled and should be left floating (unconnected). When EXTMEM is low, EECLK acts as a 3-state serial clock output to the EEPROM with a 100 μA internal pulldown.		
EEDATA/ GANGED	6	I/O	EEPROM serial data/power management mode indicator. When EXTMEM is high, EEDATA/GANGED selects between gang or per port power over-current detection for the downstream ports. When EXTMEM is low, EEDATA/GANGED acts as a serial data I/O for the EEPROM and is internally pulled down with a 100 μA pulldown. This standard TTL input must not change dynamically during operation.		
EXTMEM	26	I	EEPROM read enable. When EXTMEM is high, the serial EEPROM interface of the device is disabled. When EXTMEM is low, terminals 5 and 6 are configured as the clock and data pins of the serial EEPROM interface, respectively.		
GND	7, 28		Ground. GND terminals must be tied to ground for proper operation.		
OVRCUR1 – OVRCUR4	10, 14, 18, 22	I	Over-current input. OVRCUR1 – OVRCUR4 are active low. For per-port over current detection, one over-current input is available for each of the four downstream ports. In the ganged mode, any OVRCUR input may be used and all OVRCUR pins should be tied together. OVRCUR pins are active low inputs with noise filtering logic.		
PWRON1 – PWRON4	9, 13, 17, 21	0	Power-on/-off control signals. PWRON1 – PWRON4 are active low, push-pull outputs. Push-pull outputs eliminate the pullup resistors which open-drain outputs require. However, the external power switches that connect to these pins must be able to operate with 3.3-V inputs because these outputs cannot drive 5-V signals.		
RESET	4	ı	Reset. RESET is an active low TTL input with hysteresis and must be asserted at power up. When RESET is asserted, all logic is initialized.		
SUSPND	32	0	Suspend status. SUSPND is an active high output available for external logic power down operations. During the SUSPEND mode, SUSPND is high. SUSPND is low for normal operation.		
TSTMODE	31	I	Test pin. TSTMODE is used as a test pin during production testing. This pin must be tied to ground for normal operation.		
TSTPLL	27	I/O	Test pin. TSTPLL is used as a test pin during production testing. This pin must be tied to ground for normal operation		
VCC	3, 25		3.3-V supply voltage		
XTAL1	30	I	Crystal 1. XTAL1 is a 6-MHz crystal input with 50% duty cycle. An internal PLL generates the 48-MHz and 12-MHz clocks used internally by the ASIC logic.		
XTAL2	29	0	Crystal 2. XTAL2 is a 6-MHz crystal output. This terminal should be left open when using an oscillator.		



# absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

Supply voltage range, V <sub>CC</sub> (see Note 1)	0.5 V to 3.6 V
Input voltage range, V <sub>I</sub>	0.5 V to V <sub>CC</sub> + 0.5 V
Output voltage range, V <sub>O</sub>	0.5 V to V <sub>CC</sub> + 0.5 V
Input clamp current, $I_{IK}$ , $(V_I < 0 \text{ V or } V_I > V_{CC})$	±20 mA
Output clamp current, I <sub>OK</sub> , (V <sub>O</sub> < 0 V or V <sub>O</sub> > V <sub>CC</sub> )	±20 mA
Storage temperature range, T <sub>Stg</sub>	–65°C to 150°C
Operating free-air temperature range, T <sub>A</sub>	0°C to 70°C

<sup>†</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTE 1: All voltage levels are with respect to GND.

# recommended operating conditions

	MIN	NOM	MAX	UNIT
Supply voltage, V <sub>CC</sub>	3	3.3	3.6	V
Input voltage, TTL/LVCMOS, VI	0		VCC	V
Output voltage, TTL/LVCMOS, VO	0		VCC	V
High-level input voltage, signal-ended receiver, VIH(REC)	2		VCC	V
Low-level input voltage, signal-ended receiver, VIL(REC)			0.8	V
High-level input voltage, TTL/LVCMOS, VIH(TTL)	2		Vcc	V
Low-level input voltage, TTL/LVCMOS, V <sub>IL(TTL)</sub>	0		0.8	V
Operating free-air temperature, T <sub>A</sub>	0		70	°C
External series, differential driver resistor, R <sub>(DRV)</sub>	22 (-5%)		22 (+5%)	Ω
Operating (dc differential driver) high speed mode, f(OPRH)			12	Mb/s
Operating (dc differential driver) low speed mode, f(OPRL)			1.5	Mb/s
Common mode, input range, differential receiver, V(ICR)	0.8		2.5	V
Input transition times, t <sub>t</sub> , TTL/LVCMOS	0		25	ns
Junction temperature range, TJ	0		115	°C

# TUSB2046 4-PORT HUB FOR THE UNIVERSAL SERIAL BUS WITH OPTIONAL SERIAL EEPROM INTERFACE

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# electrical characteristics over recommended ranges of operating free-air temperature and supply voltage (unless otherwise noted)

	PARAMETER		TEST CONDITIONS	MIN	MAX	UNIT
	High-level output voltage	TTL/LVCMOS	I <sub>OH</sub> = -4 mA	VCC - 0.5		
Vон		USB data lines	$R_{(DRV)} = 15 \text{ k}\Omega$ , to GND	2.8		V
			$I_{OH} = -12 \text{ mA (without R}_{(DRV)})$	VCC - 0.5		
	Low-level output voltage	TTL/LVCMOS	I <sub>OL</sub> = 4 mA		0.5	
VOL		USB data lines	$R_{(DRV)} = 1.5 \text{ k } \Omega \text{ to } 3.6 \text{ V}$		0.3	V
		OOD data lines	$I_{OL} = 12 \text{ mA (without R}_{(DRV)})$		0.5	
\/	Positive input threshold voltage	TTL/LVCMOS			1.8	V
V <sub>IT+</sub>		Single-ended	0.8 V ≤ V <sub>ICR</sub> ≤ 2.5 V		1.8	V
\/	Negative-input threshold voltage	TTL/LVCMOS		0.8		V
VIT-		Single-ended	0.8 V ≤ V <sub>ICR</sub> ≤ 2.5 V	1		V
1/.	Input hysteresis† ( $V_{T+} - V_{T-}$ )	TTL/LVCMOS		0.3	0.7	V
V <sub>hys</sub>		Single-ended	0.8 V ≤ V <sub>ICR</sub> ≤ 2.5 V	300	500	mV
10-	Lligh impodence cutout current	TTL/LVCMOS	V = V <sub>CC</sub> or GND‡		±10	μΑ
loz	High-impedance output current	USB data lines	$0 \text{ A} \leq \text{A}^{O} \leq \text{A}^{CC}$		±10	μА
I <sub>IL</sub>	Low-level input current	TTL/LVCMOS	V <sub>I</sub> = GND		-1	μΑ
lн	High-level input current	TTL/LVCMOS	VI = VCC		1	μΑ
z <sub>o</sub> (DRV)	Driver output impedance	USB data lines	Static VOH or VOL	7.1	19.9	Ω
VID	Differential input voltage	USB data lines	0.8 V ≤ V <sub>ICR</sub> ≤ 2.5 V	0.2		V
loo	Input cumply current		Normal operation		100	mA
Icc	Input supply current		Suspend mode		1	μΑ

<sup>†</sup> Applies for input buffers with hysteresis

# differential driver switching characteristics over recommended ranges of operating free-air temperature and supply voltage, $C_L = 50$ pF (unless otherwise noted)

### full speed mode

PARAMETER		TEST CONDITIONS		MAX	UNIT
t <sub>r</sub>	Transition rise time for DP or DM	See Figure 1 and Figure 2	4	20	ns
t <sub>f</sub>	Transition fall time for DP or DM	See Figure 1 and Figure 2	4	20	ns
t(RFM)	Rise/fall time matching	$(t_{\rm f}/t_{\rm f}) \times 100$	90%	110%	
VO(CRS)	Signal crossover output voltage		1.3	2.0	V

#### low speed mode

	PARAMETER	TEST CONDITIONS			MAX	UNIT
t <sub>r</sub>	Transition rise time for DP or DM	$C_L = 200 \text{ pF to } 600 \text{ pF},$	See Figure 1 and Figure 2	75	300	ns
t <sub>f</sub>	Transition fall time for DP or DM	$C_L = 200 \text{ pF to } 600 \text{ pF},$	See Figure 1 and Figure 2	75	300	ns
t(RFM)	Rise/fall time matching	(t <sub>r</sub> /t <sub>f</sub> ) x 100		80%	120%	
V <sub>O(CRS)</sub>	Signal crossover output voltage	$C_L = 200 \text{ pF to } 600 \text{ pF}$		1.3	2.0	V



<sup>‡</sup> Applies for open drain buffers

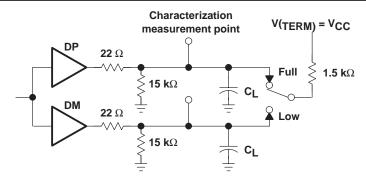
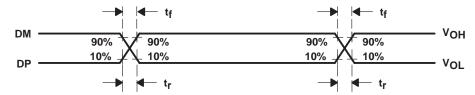


Figure 1. Differential Driver Switching Load



NOTE: The  $t_r/t_f$  ratio is measured as  $t_{r(DP)}/t_{f(DM)}$  and  $t_{r(DM)}/t_{f(DP)}$  at each crossover point.

**Figure 2. Differential Driver Timing Waveforms** 

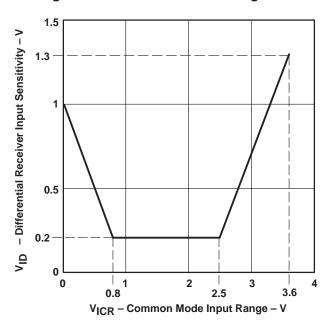


Figure 3. Differential Receiver Input Sensitivity vs. Common Mode Input Range

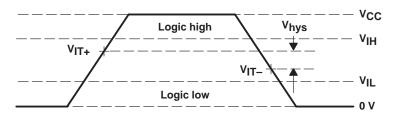


Figure 4. Single-Ended Receiver Input Signal Parameter Definitions



#### APPLICATION INFORMATION

A major advantage of USB is the ability to connect 127 functions configured in up to six logical layers (tiers) to a single personal computer (see Figure 5).

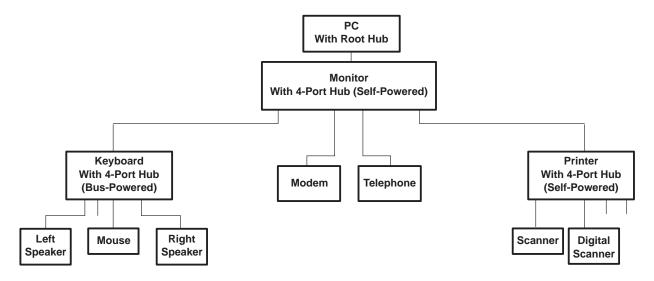


Figure 5. USB Tiered Configuration Example

Another advantage of USB is that all peripherals are connected using a standardized four wire cable that provides both communication and power distribution. The power configurations are bus-powered and self-powered modes. The maximum current that may be drawn from the USB 5-V line during power up is 100 mA. For the bus-powered mode, a hub can draw a maximum of 500 mA from the 5-V line of the USB cable. A bus-powered hub must always be connected downstream to a self-powered hub unless it is the only hub connected to the PC and there are no high-powered functions connected downstream. In the self-powered mode, the hub is connected to an external power supply and can supply up to 500 mA to each downstream port. High-powered functions may draw a maximum of 500 mA from each downstream port and may only be connected downstream to self-powered hubs. Per the USB specification, in the bus-powered mode, each downstream port can provide a maximum of 100 mA of current, and in the self-powered mode, each downstream port can provide a maximum of 500 mA of current.

Both bus-powered and self-powered hubs require over-current protection for all downstream ports. The two types of protection are individual port management (individual port basis) or ganged port management (multiple port basis). Individual port management requires power management devices for each individual downstream port, but adds robustness to the USB system because, in the event of an over-current condition, the USB host only powers down the port that has the condition. The ganged configuration uses fewer power management devices and thus has lower system costs, but in the event of an over-current condition on any of the downstream ports, all the ganged ports are disabled by the USB host.

Using a combination of the BUSPWR and EEDATA/GANGED inputs, the TUSB2046 supports four modes of power management: bus-powered hub with either individual port power management or ganged port power management, and the self-powered hub with either individual port power management or ganged port power management. Texas Instruments supplies the complete hub solution because we offer this TUSB2046, the TUSB2073 (7–port) and the TUSB2140B (4-port with I<sup>2</sup>C) hubs along with the power management chips needed to implement a fully USB Specification 1.1 compliant system.



#### APPLICATION INFORMATION

#### **USB** design notes

The following sections provide block diagram examples of how to implement the TUSB2046 device. Please note, even though no resistors are shown, pullup, pulldown and series resistors must still be used to properly implement this device. Figure 1 shows a few resistors that must be used for the USB lines, and for a general reference design, one is available on the TI USB web site at Http://www.ti.com/sc/usb.

Figure 6 is a block diagram example of how to connect the external EEPROM if a custom Product ID and Vendor ID are desired.

Figure 7 is an example of how to generate the 6-MHz clock signal. Figure 8 shows the EEPROM Read Operation Timing Diagram. Figures 9, 10, and 11 illustrate how to connect the TUSB2046 device for different power source and port power management combinations.

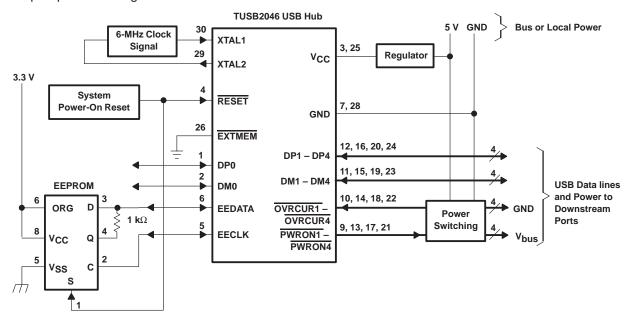
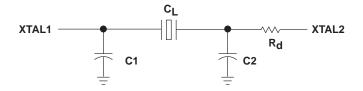


Figure 6. Typical Application of the TUSB2046 USB Hub



NOTE A: Figure 7 assumes a 6 MHz fundamental crystal that is parallel loaded. The component values of C1, C2 and  $R_d$  were determined using a crystal from Fox Electronics – part number HC49U–6.00MHz30\50\0  $\pm$ 70\20 which means  $\pm$ 30 ppm at 25°C and 50 ppm from 0°C to 70°C. The characteristics for the crystal are load capacitance ( $C_L$ ) of 20 pF, maximum shunt capacitance ( $C_0$ ) of 7 pF and the maximum ESR of 50  $\Omega$ . In order to insure enough negative resistance, use C1 = C2 = 27 pF. The resistor  $R_d$  is used to trim the gain, and  $R_d$  = 1.5 k $\Omega$  is recommended.

Figure 7. Crystal Tuning Circuit



#### **APPLICATION INFORMATION**

#### programming the EEPROM

An SGS Thompson M93C46 EEPROM or equivalent is used for storing the programmable VID and PID. When the EEPROM interface is enabled ( $\overline{\text{EXTMEM}} = 0$ ), the EECLK and EEDATA are internally pulled down ( $100 \,\mu\text{A}$ ) inside the TUSB2046. The internal pulldowns are disabled when the EEPROM interface is disabled ( $\overline{\text{EXTMEM}} = 1$ ).

The EEPROM is programmed with the three 16-bit locations as shown in Table 1. Connecting pin 6 of the EEPROM high (ORG = 1) organizes the EEPROM memory into  $64 \times 16$  bit words.

**Table 1. EEPROM Memory Map** 

ADDRESS	D15	D14	D13	D12-D8	D7-D0	
00000	0	GANGED	00000	00000	00000000	
00001		VID F	VID Low-byte			
00010	PID High-byte PID Low-byte					
	XXXXXXXX					

The D and Q signals of the EEPROM must be tied together using a 1 k $\Omega$  resistor with the common I/O operations forming a single-wire bus. After system power-on reset, the TUSB2046 performs a one-time access read operation from the EEPROM if the  $\overline{\text{EXTMEM}}$  pin is pulled low and the chip select(s) of the EEPROM is connected to the system power-on reset. Initially, the EEDATA pin will be driven by the TUSB2046 to send a start bit (1) which is followed by the read instruction (10) and the starting-word address (00000). Once the read instruction is received, the instruction and address are decoded by the EEPROM, which then sends the data to the output shift register. At this point, the hub stops driving the EEDATA pin and the EEPROM starts driving. A dummy (0) bit is then output and the first three 16-bit words in the EEPROM are output with the most significant bit (MSB) first.

The output data changes are triggered by the rising edge of the clock provided by the TUSB2046 on the EECLK pin. The *SGS-Thompson M936C46* EEPROM is recommended because it advances to the next memory location by automatically incrementing the address internally. Any EEPROM used must have the automatic internal address advance function. After reading the three words of data from the EEPROM, the TUSB2046 puts the EEPROM interface into a high-impedance condition (pulled down internally) to allow other logic to share the EEPROM. The EEPROM read operation is summarized in Figure 8. For more details on EEPROM operation, refer to *SGS-Thompson Microelectronics M93C46 Serial Microwire Bus EEPROM* data sheet.



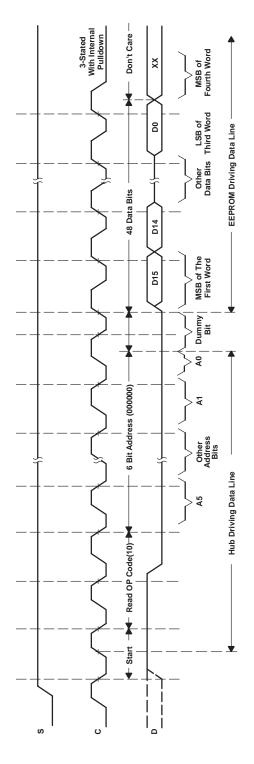


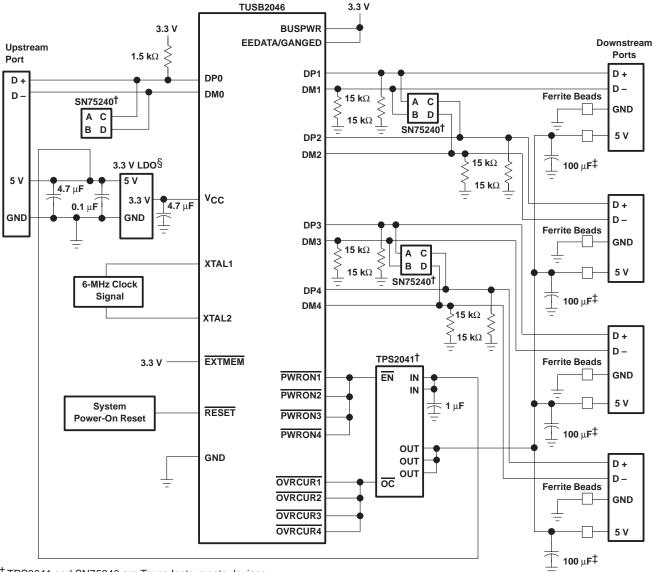
Figure 8. EEPROM Read Operation Timing Diagram



#### **APPLICATION INFORMATION**

#### bus-powered hub, ganged port power management

When used in bus-powered mode, the TUSB2046 supports up to four downstream ports by controlling a TPS2041 device which is capable of supplying 100 mA of current to each downstream port. Bus-powered hubs must implement power switching to ensure current demand is held below 100 mA when the hub is hot-plugged into the system. Utilizing the TPS2041 for ganged power management provides over-current protection for the downstream ports. The SN75240 transient suppressors reduce inrush current and voltage spikes on the data lines. The OVRCUR signals should be tied together for a ganged operation.



<sup>†</sup> TPS2041 and SN75240 are Texas Instruments devices.

Figure 9. TUSB2046 Bus-Powered Hub, Ganged Port Power Management Application



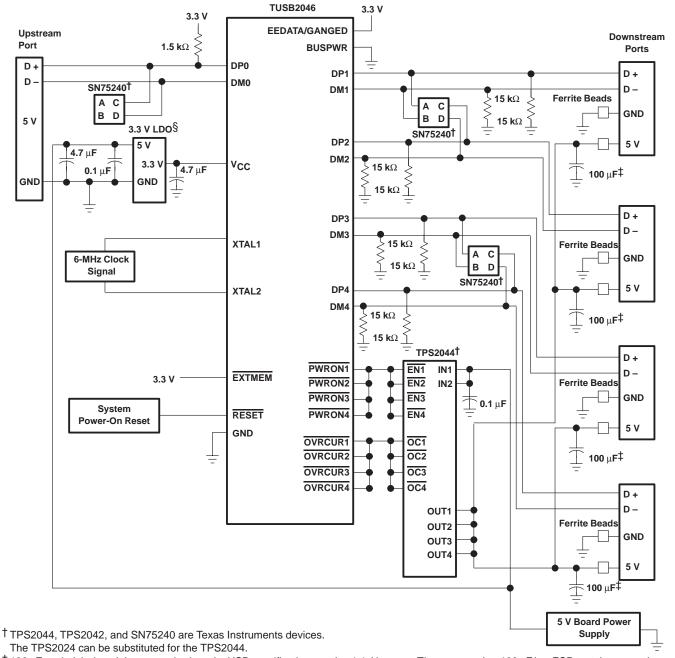
<sup>‡ 120</sup> μF per hub is the minimum required per the USB specification, version 1.1. However, TI recommends a 100 μF low ESR tantulum capacitor per port for immunity to voltage droop.

<sup>§</sup> LDO is a 5 V to 3.3 V voltage regulator

#### APPLICATION INFORMATION

#### self-powered hub, ganged port power management

The TUSB2046 can also be implemented for ganged port power management in a self-powered configuration. The implementation is very similar to the bus-powered example with the exception that a self-powered port supplies 500 mA of current to each downstream port. The over-current protection can be provided by a TPS2044 quad device or a TPS2024 single power switch.



<sup>‡ 120</sup> μF per hub is the minimum required per the USB specification, version 1.1. However, TI recommends a 100 μF low ESR tantulum capacitor per port for immunity to voltage droop.

Figure 10. TUSB2046 Self-Powered Hub, Ganged Port Power Management Application

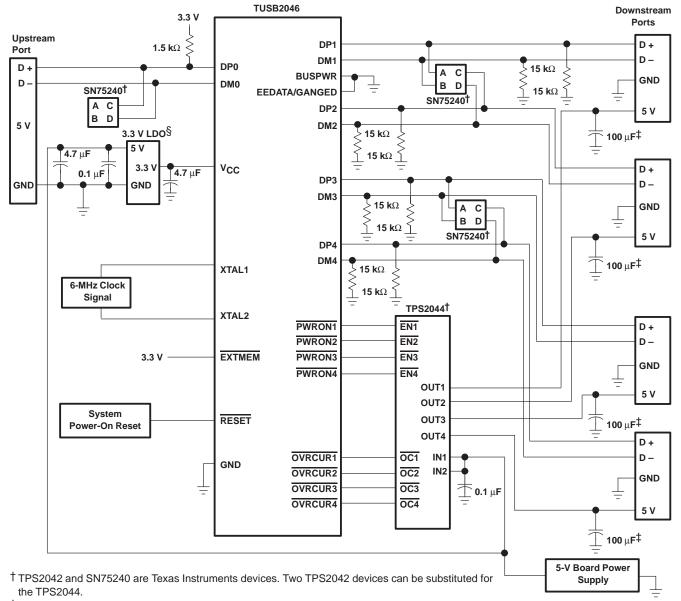


<sup>§</sup> LDO is a 5 V to 3.3 V voltage regulator

#### **APPLICATION INFORMATION**

#### self-powered hub, individual port power management

In a self-powered configuration, the TUSB2046 can be implemented for individual port-power management when used with the TPS2044 because it is capable of supplying 500 mA of current to each downstream port and can provide current limiting on a per port basis. When the hub detects a fault on a downstream port, power is removed from only the port with the fault and the remaining ports continue to operate normally. Self-powered hubs are required to implement over-current protection and report overcurrent conditions. The SN75240 transient suppressors reduce inrush current and voltage spikes on the data lines.



<sup>‡ 120</sup> μF per hub is the minimum required per the USB specification, version 1.1. However, TI recommends a 100 μF low ESR tantulum capacitor per port for immunity to voltage droop.

Figure 11. TUSB2046 Self-Powered Hub, Individual Port-Power Management Application

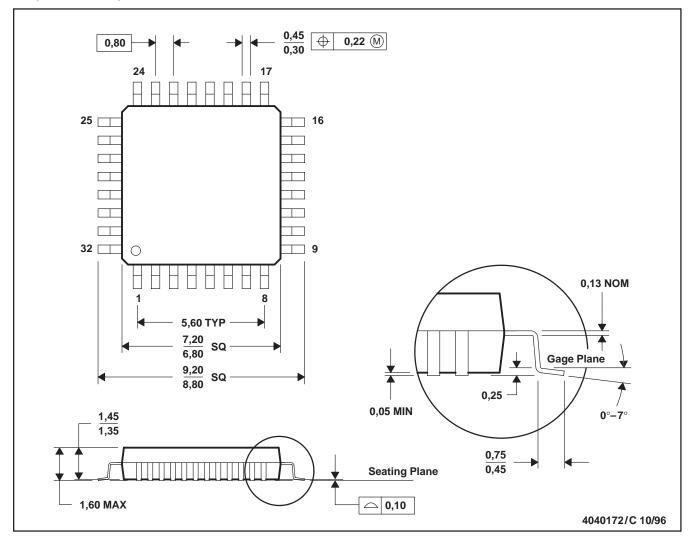


<sup>§</sup> LDO is a 5 V to 3.3 V voltage regulator

#### **MECHANICAL DATA**

### VF (S-PQFP-G32)

#### PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Falls within JEDEC MS-026

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